Optical carrier wave shocking: Detection and dispersion

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Carrier wave shocking is studied using the pseudospectral spatial-domain (PSSD) technique. We describe the shock detection diagnostics necessary for this numerical study and verify them against theoretical shocking predictions for the dispersionless case. These predictions show a carrier envelope phase and pulse bandwidth sensitivity in the single-cycle regime. The flexible dispersion management offered by the PSSD enables us to independently control the linear and nonlinear dispersion. Customized dispersion profiles allow us to analyze the development of both carrier self-steepening and shocks. The results exhibit a marked asymmetry between normal and anomalous dispersion, both in the limits of the shocking regime and in the (near) shocked pulse wave forms. Combining these insights, we offer some suggestions on how carrier shocking (or at least extreme self-steepening) might be realized experimentally.

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I. INTRODUCTION

The self-steepening of an optical pulse envelope was first studied by DeMartini *et al.* in [1](#page-7-0)967 [1] and is a well-known phenomenon associated with self-phase modulation (SPM). Surprisingly, however, the possibility of self-steepening of the optical carrier wave¹ was considered even earlier in a 1965 paper by Rosen $[2]$ $[2]$ $[2]$, who showed that, for a third-order $\chi^{(3)}$ nonlinearity (and under suitable conditions), a shock (or field discontinuity) develops in a finite distance. This latter phenomenon received little attention for more than 30 years, until it was revisited in the 1990s by Moloney and coworkers $[3,4]$ $[3,4]$ $[3,4]$ $[3,4]$, who performed finite difference time-domain (FDTD) simulations of the process. Three-dimensional (3D) FDTD simulations of carrier shocking have recently been performed by Trillo *et al.* [[5](#page-7-4)].

In the present paper, we investigate carrier wave shocking in $\chi^{(3)}$ nonlinear materials where SPM is accompanied by the generation of (odd) higher harmonics. For the dispersionless case we have generalized earlier predictions based on the method of characteristics (MOC) to allow for arbitrary initial wave forms. This allows us, for example, to predict the carrier envelope phase (CEP) sensitivity of the shocking distance for optical pulses, as well as the dependence on pulse length.

Our primary interest in this paper is the effect of linear dispersion on carrier shock formation. Since no analytic solutions exist in this case, we are forced to rely on numerical simulations. In any discussion of carrier wave shocking, it is important to distinguish between three related concepts: the physical system, the mathematical model, and the numerical model. The mathematical model is an approximation to the physical system, while the numerical model is an approximation to the mathematical model. Actual discontinuities occur only in the mathematical model, and it is these to which the idea of shock formation refers. In the physical system, discontinuities are prevented by phenomena not included in the mathematics, while numerical codes inevitably fail as a mathematical discontinuity is approached. The indicator of an imminent "shock" is the rapidly increasing gradient (steepening) of the optical carrier. In the numerical model, we see numerical symptoms generated by extreme selfsteepening, and these correlate with the onset of discontinuities in the mathematical model. Under these circumstances, it has been necessary for us to develop a quantitative numerical test of "shock formation." We have found the most satisfactory diagnostic to be "local discontinuity detection" (LDD), which gives results that are in good agreement with theoretical MOC predictions based on the mathematical model. LDD provides a clear numerical measure of the rapid steepening that precedes the appearance of a discontinuity in the mathematical representation. We continue to use the term "shock" to describe the situation where a mathematical shock is imminent.

In our simulations, we exploit the flexibility in dispersion management offered by the pseudo spectral spatial-domain (PSSD) technique $[6]$ $[6]$ $[6]$ to study carrier shock formation for a range of simple dispersion profiles and determine the degree of phase mismatch that carrier shocking can tolerate. As expected, we find that shocking occurs when the nonlinearity dominates the linear dispersion. However, it emerges that the process is asymmetric, with anomalous dispersion being far more conducive to shocking than normal dispersion. Hence, the fact that the LDD scheme does not detect carrier shocks in simulations involving (normally dispersive) fused silica, even at powers equal to its damage threshold, is neither surprising nor necessarily discouraging. After all, anomalously dispersive materials could potentially be engineered. Further, our results also relate to how one might perform carrier shaping (as opposed to carrier steepening), a process that has some interesting applications.

After briefly describing our simulation methods in Sec. II, we consider dispersionless shocking and the method of characteristics in Sec. III and our LDD shock detection scheme in Sec. IV. Then we discuss the effect of dispersion on carrier shocking in Sec. V, followed by our numerical results in Sec.

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¹Note that in this paper we use the term "carrier" to denote all the oscillations of the field and do not use its other sense—i.e., that of fixed-frequency oscillations as used in a envelope and carrier representation a pulse.

VI. In Sec. VII we consider the potential relevance to experimental detection of carrier steepening and/or shocks. Finally, in Sec. VIII, we present our conclusions.

II. SIMULATION METHODS

The PSSD method $[6,7]$ $[6,7]$ $[6,7]$ $[6,7]$ offers significant advantages over the traditional FDTD and pseudospectral time-domain (PSTD) [[8](#page-7-7)] techniques for modeling the propagation and interaction of few-cycle pulses. Run times are generally faster, and the PSSD method also offers far greater flexibility in the handling of dispersion. Whereas the FDTD and PSTD methods $\begin{bmatrix} 8 \end{bmatrix}$ $\begin{bmatrix} 8 \end{bmatrix}$ $\begin{bmatrix} 8 \end{bmatrix}$ propagate fields $E(z)$ and $H(z)$ forward in *time*, the PSSD method propagates fields $E(t)$ and $H(t)$ forward in *space*. It is important to keep this difference in mind when comparing our results to those in $[8]$ $[8]$ $[8]$. Under the PSSD approach, the entire time history (and therefore frequency content) of the pulse is known at any point in space, so arbitrary dispersion incurs no extra computational penalty. In contrast, the FDTD or PSTD approaches use convolutions incorporating time-response models for dispersion.

We apply the PSSD algorithm to two representations of the field and source-free Maxwell's equations in nonmagnetic media; the first uses the *E* and *H* fields and the second the directional fields $\vec{G}^{\pm}(t) = \alpha_r(t) * \vec{E}_x(t) \pm \beta_r \vec{H}_y(t)$ [[9](#page-7-8)], where $*$ stands for a convolution in time. Here the α_r and β_r include the (linear) permittivity and permeability of the material [i.e., $\epsilon(t), \mu$]. These G^{\pm} fields enable us to rewrite Maxwell's equations and efficiently separate out the relevant forwardgoing part of the field.

For an instantaneous $\chi^{(3)}$ nonlinearity, the equations for *E* and H in the 1D (plane-wave) limit are

$$
\frac{dH_y(t;z)}{dz} = -\frac{d}{dt} [\epsilon_0 \epsilon_r(t) * E_x(t;z) + \chi^{(3)} E_x(t;z)^3], \quad (1)
$$

$$
\frac{dE_x(t;z)}{dz} = -\frac{d}{dt}[\mu_0 H_y(t;z)].
$$
\n(2)

The *G*[±]-field simulations usually assume *G*[−]=0 and, as a result, contain only forward-traveling components. The forward-only wave equation for *G*⁺ is

$$
\frac{dG^{+}(t;z)}{dz} = -\frac{d}{dt}[\beta_r \alpha_r(t) * G^{+}(t;z) + \beta_r \chi^{(3)} E(t;z)^3], \quad (3)
$$

where it is most straightforward to calculate the nonlinear term by reconstructing $E(t; z)$ from $G^+(t; z)$ in the frequency domain using $\tilde{E}(\omega; z) = \tilde{G}^+(\omega; z)/2\tilde{\alpha}_r(\omega)$, since $G^{\text{-}}=0$. Notice the similarity between Eqs. (1) (1) (1) and (3) (3) (3) , but that Eq. (3) propagates the field in a single first-order equation, rather than two.

Typical array sizes used in pulse simulations were *N* $= 2^{14}$ covering a time window $T = 200$ fs, and (spatial) propagation steps were $dz = 0.4cT/N \approx 0.9$ nm. We ensured the stability of our integration using Orszag's $2/3$ rule $\lceil 10 \rceil$ $\lceil 10 \rceil$ $\lceil 10 \rceil$, which involves setting the upper part of the spectral range to zero. It is worth noting that changing this cutoff, either by adjusting its position or by using a smoothed (rather than steplike)

FIG. 1. (Color online) The profile of a few-cycle optical pulse just prior to shocking in the dispersionless limit. The larger oscillations in the center of the pulse undergo more self-steepening than those in the wings. The standard pulse parameters were used.

filter, made little difference to test simulations. The pulse profile used as an initial condition was

$$
E(t) = E_0 \sin(\omega_1 t + \phi) \operatorname{sech}(0.28\omega_1 t/\tau), \tag{4}
$$

where our standard parameters were $\omega_1 = 2.356 \times 10^{15}$ rad/s (i.e., $\lambda = 800$ nm) with $\tau = 0.93$. Such pulses are rather short since the number of cycles inside the intensity full width at half maximum (FWHM) is τ , but in fact the shocking distance is only weakly dependent on the pulse width, with significant variation only appearing for pulses of a few cycles or less.

We also performed continuous wave (cw) simulations, for which we modeled just a single cycle of the carrier assisted by the periodic nature of the discrete Fourier transform. For these we used array sizes of $N=2^{10}$, and the time window was set by the period of the field oscillations.

Our default value of nonlinear strength was $\chi^{(3)}E_0^2 = 0.02$, which is comparable to that in fused silica at an intensity of 0.7×10^{14} W/cm²; our $\chi^{(3)}$ parameter is equivalent to η in Rosen $\lceil 2 \rceil$ $\lceil 2 \rceil$ $\lceil 2 \rceil$ and *a* in Gilles *et al.* $\lceil 4 \rceil$ $\lceil 4 \rceil$ $\lceil 4 \rceil$. We use an instantaneous nonlinearity, since our primary interest is linear dispersion, and that is a far more significant effect than the nonlinear time response.

III. CARRIER WAVE SHOCKING

As an introduction to the process of carrier wave shocking, Fig. [1](#page-1-2) shows the profile of a pulse propagating in a dispersionless $\chi^{(3)}$ medium, just before a shock occurs. The nonlinearity gives rise to a nonlinear index of refraction, n_2E^2 , the effect of which is to increase the effective refractive index in the more intense regions of the profile. This reduces the phase velocity at the peak of each oscillation with respect to the rest of the wave form and causes the slope on the trailing edges to increase dramatically.

The effects seen in Fig. [1](#page-1-2) are associated with the generation of third and higher harmonics, although the harmonic components are not particularly strong even when a shock is about to occur. As an example, Fig. [2](#page-2-0) shows how the harmonics build up as shocking is approached. The ω^4 scaling of the intensity spectrum in the figure exaggerates the contribution of the higher orders and has been chosen for illustrative purposes. Notice that the profile becomes nearly flat

FIG. 2. Development of the heights of the scaled harmonic peaks as a pulse approaches the (LDD) shocking distance of 4.3 μ m in the dispersionless case. Each line perpendicular to the ω/ω_1 axis corresponds to the (scaled) contribution from that spectral peak. Note that the viewpoint has been rotated so that the contribution from the fundamental is to the *right*. The initial pulse contained about 33 cycles $(\tau = 33)$.

i.e., the spectrum falls off as the fourth power of the frequency) just before shocking is registered at around 4.3 μ m. If we write

$$
E = A(t)[\sin(\omega_1 t) + \gamma \cos(3\omega_1 t + \psi)], \tag{5}
$$

we find that an appropriate choice of $A(t)$, with $\gamma = 0.1$ and ψ =0, gives us a passable match to Fig. [1.](#page-1-2) Note that this choice of ψ corresponds to the phase of third-harmonic generation (THG) under index matched conditions-i.e., where $n_0=n(\omega_1)=n(\omega_3).$

Rosen's original paper $\lceil 2 \rceil$ $\lceil 2 \rceil$ $\lceil 2 \rceil$ used the MOC to predict the formation of a value discontinuity in the field at certain points within the profile. If the displacement of the dispersionless medium is written

$$
D = \epsilon_0 (E + \chi^{(1)} E + \chi^{(3)} E^3), \tag{6}
$$

he showed that the wave equation for *E* is

$$
c^2 \frac{\partial^2 E}{\partial x^2} = (1 + \chi^{(1)}) \frac{\partial^2 E}{\partial t^2} + \chi^{(3)} \frac{\partial^2 E^3}{\partial t^2}
$$
 (7)

and that the associated equation governing the characteristic lines of *E* is

$$
\frac{\partial E}{\partial t} + v(E) \frac{\partial E}{\partial x} = 0.
$$
 (8)

Here, the velocity $v(E)$ is given by

$$
v(E) = \frac{c}{(\epsilon_r + 3\chi^{(3)}E^2)^{1/2}},
$$
\n(9)

where $\epsilon_r = 1 + \chi^{(1)} = n_0^2$ is the (relative) dielectric constant and n_0 the linear refractive index.

Using Eq. (9) (9) (9) along with the construction shown in Fig. [3,](#page-2-2) we can derive a simple formula for the distance to shocking. The figure shows two characteristics *AC* and *BC*, originating from points *A* and *B* and converging towards a shock at *C* after a distance of *L*. The intensity at *A* is higher than at *B*, so

FIG. 3. Method of characteristics. Two points *A* and *B* on the field profile, separated initially by a time difference *dt*, travel at different speeds *v*−*dv* and *v*, and meet at point *C*.

the speed associated with AC (represented by its gradient) is lower than that of *BC*. This means that at *C*, the field has two values and a discontinuity has formed. From the geometry of the figure, it is easy to show that

$$
\frac{dv}{dt} = \frac{v}{t} = \frac{v^2}{L} = \frac{(c/n_0)^2}{L},
$$
\n(10)

where *t*, $v = c/n_0$, and $L = vt$ are, respectively, time, speed, and distance.

On the other hand, differentiating Eq. ([9](#page-2-1)) leads to

$$
\frac{dv}{dt} = -\frac{3c\chi^{(3)}}{2[n_0^2 + 3\chi^{(3)}E^2]^{3/2}} \frac{d(E^2)}{dt},\tag{11}
$$

and this combined with Eq. (10) (10) (10) yields

$$
L = \frac{cn_0\sqrt{1 + 3\chi^{(3)}E^2/n_0^2}}{3\chi^{(3)}(-dE^2/dt)}
$$
(12)

$$
=\frac{c}{4n_2}\frac{\sqrt{1+8n_2E^2/n_0}}{(-dE^2/dt)},
$$
\t(13)

where $n_2 = 3\chi^{(3)}/8n_0$ is the material parameter determining the intensity-induced refractive index shift as n_2E^2 . For a given profile, a shock will occur first at the point where *−dE²/dt* reaches its negative extremum. We can therefore define the shocking distance as

$$
L_{shock} = \frac{c}{4n_2} \min \frac{\sqrt{1 + 8n_2 E^2/n_0}}{(-dE^2/dt)} \tag{14}
$$

$$
\approx \frac{c}{4n_2} \min \frac{1}{(-dE^2/dt)} \quad \text{for } 8n_2 E^2 / n_0 \ll 1. \tag{15}
$$

This formula is more general than that of either Rosen $\lceil 2 \rceil$ $\lceil 2 \rceil$ $\lceil 2 \rceil$ or Gilles *et al.* [[4](#page-7-3)]. Notice in particular that the parameter that controls the shock behavior is not the gradient of the field (dE/dt), but that of the field squared (dE^2/dt) .

For a sinusoidal initial wave form $E = E_0 \sin(\omega_1 t + \phi)$, it is easy to show that shocks form at

FIG. 4. MOC shocking distances as a function of phase, for pulses as in Eq. ([4](#page-1-3)), allowing for different pulse lengths. We include the $1/2$ cycle $\tau = 0.56$ results to emphasize the trend, but even for a long pulse (τ =28), a small peak can be seen just below ϕ/π = 0.01. The peak position is weakly τ dependent. The + signs denote LDD shocking distances obtained from simulations of the τ $= 0.93$ case.

$$
\omega_1 t = -\pi/4 + j\pi - \phi,\tag{16}
$$

where *j* is an integer, and that the shocking distance is

$$
L_{shock} = \frac{2cn_0}{3\omega_1\chi^{(3)}E_0^2} = \frac{c}{4\omega_1n_2E_0^2}.
$$
 (17)

The approach is readily extended to pulsed wave forms of the type defined in Eq. ([4](#page-1-3)). Analytical results can be derived in the new situation in which Eq. (16) (16) (16) becomes a transcendental equation. However, the results are cumbersome and it is simpler to scan the profile numerically to determine the shocking parameters. It turns out that the shocking distance for short pulses exhibits an interesting sensitivity to the carrier envelope phase ϕ . While in the cw case all locations defined by Eq. (16) (16) (16) were equivalent, for pulses, the one nearest the peak of the envelope has a shorter *Lshock* than the others.

A set of results is displayed in Fig. [4](#page-3-1) where the shocking distance is plotted as a function of the carrier phase ϕ for sech profiles with different pulse widths τ . The dotted line is for the case of a very broad pulse for which *Lshock* is given by Eq. ([17](#page-3-2)). The sharp peaks mark a curve crossing where the shock location switches from one point on the sinusoid to another. Notice that the range of shocking distances increases for shorter pulses and that, unsurprisingly, the lowest values occur when ϕ is around– $\pi/2$ i.e., when the pulse has a cosine form.

One very important point to note from Fig. [4](#page-3-1) is that for pulses containing more than a few cycles, the dependence of the shocking distance on pulse width is very weak. We will see this message repeated later in Sec. V, with shock regions being similar for both single-cycle $(\tau=1)$ pulses and cw $(\tau$ $=\infty$) fields.

IV. SHOCK DETECTION

Since optical shock formation is directly associated with regions of increasingly steep field gradient, any numerical scheme, however sophisticated, is bound to fail at some point in the process. We therefore want to recognize when a shock

FIG. 5. The profile of a few-cycle optical pulse at the point of shocking. The larger oscillations in the center of the pulse undergo more self-steepening than those in the wings. (a) The whole pulse, with the LDD carrier shock circled (O) . (b) An expanded view of the shock region, with its point of inflection (at \sim 9.3 fs) being very close to the steepest gradient (at \sim 9.1 fs). The standard pulse parameters were used.

is imminent, not only to avoid numerical problems, but as a means to estimate the distance at which a discontinuity would occur in the mathematical model.

One obvious symptom of impending numerical failure is loss of energy conservation $\lceil 6 \rceil$ $\lceil 6 \rceil$ $\lceil 6 \rceil$. However, this does not give an indication at the first instance of a shock forming, but rather signals the accumulated effect of multiple small numerical failures from many shocked regions.

A more physical strategy is to search for regions where the field gradient *dE*/*dt* is large and increasing rapidly and to use this to predict the shocking point. A useful variant, suggested by the MOC calculation in the previous section, is to use the value of $-dE^2/dt$ instead of the gradient.

Overall, we find that the best method is local discontinuity detection, which is similar to techniques used in other fields (see, e.g., $[11]$ $[11]$ $[11]$). As the shock regime is approached, narrow shoulders with associated points of inflection appear within the regions of rapidly increasing gradient. The procedure is therefore to scan the field profile for the maximum gradient (of either *E* or E^2) and, if it occurs near a point of inflection, an incipient shock is registered. An example of a pulse that has just triggered the LDD diagnostic is shown in Fig. [5.](#page-3-3)

The LDD method requires two parameters. The first determines the time scale used in determining whether a point of inflection exists. For this, we pick the scale set by our temporal grid and insist that the field gradients calculated at three adjacent grid points have opposing signs: either updown-up or down-up-down. The second determines the maximum range allowed between the maximum gradient and the point of inflection, and our default value for this was ten

FIG. 6. The LDD shocking distance as a function of refractive index, comparing the approximate MOC prediction from Eq. (15) (15) (15) to PSSD simulations $(+)$ for pulses with $\tau=0.93$. Other PSSD simulation results from independent codes give very similar results to those shown in the graph.

grid points. In our simulations, we see that the position of the first detected shock depends only weakly on this range. We can easily minimize the small sensitivity to these parameters by holding them fixed throughout any given set of simulations. As a result, we have found LDD to be a sensitive and reliable method of shock detection.

Equation ([17](#page-3-2)) predicts that the shocking distance should increase linearly with the refractive index n_0 . We use this to test the LDD diagnostic in Fig. [6,](#page-4-0) where the analytical formula is compared with the results of numerical simulations. This figure shows close agreement between prediction using Eq. (15) (15) (15)] and simulation, where the approximation causes the MOC prediction to be reduced by less than 0.1 μ m at n_0 =1. We see similar agreement between simulations using the LDD method and the carrier phase sensitivity shown in Fig. [4.](#page-3-1) The presence of small systematic differences (as in, e.g., Figs. [4](#page-3-1) and [6](#page-4-0)) can be easily understood, since the LDD diagnostic is (strictly speaking) a test of the numerics and is not a direct test for the presence of a physical shock or mathematical discontinuity.

V. EFFECT OF DISPERSION ON SHOCKING

The primary purpose of this paper is to understand the principles of carrier shock formation in the presence of dispersion. Some simple ideas about the role of dispersion can be understood from Eq. (5) (5) (5) using the insight from Eqs. (10) (10) (10) – (15) (15) (15) –i.e., that the rate of change of E^2 is the critical factor in shock development, rather than that of *E*. If only the fundamental and third-harmonic components are considered [as in Eq. (5) (5) (5)], the effective refractive indices are

$$
\Delta n_{NL:1} = n_1 + n_2(1 + 3\gamma^2)I_1,\tag{18}
$$

$$
\Delta n_{NL:3} = n_3 + n_2(3 + \gamma^2)I_1. \tag{19}
$$

Evidently, the relative phase velocity of the two waves is affected by both linear and nonlinear dispersion, so the phase ψ in Eq. ([5](#page-2-5)) will vary accordingly as the pulse propagates. Figure [7,](#page-4-1) which shows how dE^2/dt varies with ψ , suggests that shocking is likely to be exacerbated when ψ is small and positive, but moderated when ψ is negative. Broadly speaking, the former case will be promoted by anomalous disper-

FIG. 7. The effect of different time lags between fundamental and third harmonics on the steepness of the pulse. The field profile is as in Eq. ([5](#page-2-5)), with $A(t)=A_0$ and $\gamma=1/16$. (a) Scaled maximum values of $M_j = \max(dE^j/dt)$ as a function of third-harmonic phase offset ψ . We can see that the maxima of dE/dt and dE^2/dt occur at different ψ . (b) Position on the pulse $\theta_j = \omega_1 t_j$ of the maxima plotted in the top frame. Note that the kinks in (a) and (b) occur for offsets that give the longest shocking distances, not the shortest.

sion and the latter by normal dispersion; however, the process is clearly complicated, since it involves time-dependent phase shifts between the waves and the interplay of linear and nonlinear dispersion. Of course, since carrier shocking relies on the establishment and maintenance of specific phase relationships between a set of harmonics, it must be expected that strong dispersion of either sign will disrupt the shock formation process. On the other hand, the simple argument that has been offered suggests that shocking may be tolerant to a degree of anomalous dispersion, but not to a similar amount of normal dispersion. In general, therefore, a graph of shocking signature versus refractive index mismatch might be expected to exhibit a shock region where nonlinearity dominates the dispersion (displaced in the direction of anomalous dispersion), surrounded by a shock-free region where dispersion dominates the nonlinearity. Moreover, if a dominant coherence length L_C can be defined, it is reasonable to expect shocking to occur when this exceeds the characteristic SPM length (L_{SPM}) . As we shall see, all these features are borne out by the numerical results.

In our numerical simulations, we make extensive use of model dispersion curves, which enable refractive index differences between harmonics to be freely controlled and lead to uncomplicated boundaries between the shock and noshock regimes. The dispersion profiles shown in Fig. [8](#page-5-0) duly contain either refractive index steps Δn at the midpoints between successive odd harmonics or smooth gradients δ that provide a similar net change. In the simplest option, there is a single step at $2\omega_1$, in which case the dominant coherence length is clearly $L_C = \pi / |k_3 - 3k_1| = \pi c / 3 \omega_1 |n_3 - n_1|$; we have

FIG. 8. Types of refractive index profile used. The *solid* lines show a single refractive index step midway between ω_1 and ω_3 , so that the fundamental is always phase mismatched from its higher harmonics, although they remain perfectly phase matched with each other. The *dashed* lines show multiple refractive index steps, each of the same size and always midway between subsequent harmonics. The *dotted* lines show a linear refractive index gradient which gives the same mismatch between subsequent harmonics as the multistepped case. We do not show lines for the case of a single step at $4\omega_1$ to avoid cluttering the figure.

also tried a single step at $4\omega_1$, which has a shorter L_c . In all cases, when *n* increases with frequency, the situation corresponds broadly to normal dispersion, while decreasing *n* corresponds to anomalous dispersion. The step size (or gradient) is chosen to be comparable to values in fused silica at ω_1 $= 1.5$ rad/fs, where the refractive index differences between the lower harmonics are $\Delta n_{1,3} \approx 0.06$ and $\Delta n_{3,5} \approx 0.12$ [[4](#page-7-3)]. While we consider the case of fused silica itself in Sec. VII, the results based on the model dispersion characteristics are invaluable for understanding the essential principles of carrier shock formation in dispersive media.

VI. RESULTS AND DISCUSSION

We will now analyze our numerical simulations of carrier shocking in the presence of dispersion on the basis of the principles discussed above. Results are included for both a cw and for a single-cycle pulse. The cw case gives slightly wider shocking regions, but the differences are minor. This is because the effect of the pulse envelope on the field amplitudes and gradients of the central carrier oscillation is small, except when considering subcycle pulses. In the results we present, the energy conservation and LDD measures reveal the presence of sharp boundaries between the shocking and nonshocking regions.

Results for single refractive index steps at $2\omega_1$ and $4\omega_1$ are presented in Figs. [9](#page-5-1) and [10,](#page-5-2) respectively, whereas Fig. [11](#page-6-0) has a step midway between all harmonics. In both singlestepped cases, a useful coherence length can be defined on the basis of the mismatch between the fundamental and the harmonic just above the step. In the multistepped case, there is no easy way to define a dominant coherence length.

Figure $9(a)$ $9(a)$ shows the pulse profiles in the anomalous (negative) and normal (positive) single-step cases for the smallest step size at which shocking did *not* occur. The first obvious difference between the profiles is the opposite walkoff direction of the third harmonic, although the thirdharmonic contribution is hard to see in the anomalous case.

FIG. 9. (Color online) Carrier shocking for cw and pulsed (τ (20.93) cases with a single refractive index step at $2\omega_1$. Frame (a) compares chirped pulses at a 40- μ m propagation distance from the nonshock region immediately outside of the shocked region; the upper curve (X) is for the negative step, the lower (Y) for the positive step. Frame (b) shows the correlation in the region where $L_c \leq L_{SPM}$ between energy conservation failure *(logarithmic* righthand scale, dots) and the LDD-detected shocking distance (lefthand scale, solid line). The dotted line shows the LDD results for a cw field $(\tau = \infty)$.

The second is that the pulse profiles exhibit distinctly different characteristics according to the sign of the dispersion. Narrow spikes are visible in the anomalous case, whereas profiles with more rounded maxima occur for normal dispersion. A possible interpretation is suggested by Fig. [7,](#page-4-1) where

FIG. 10. (Color online) Carrier shocking for cw and pulsed (τ = 0.93) cases with a single refractive index step at $4\omega_1$, showing the correlation in the region where $L_C \leq L_{SPM}$ between energy conservation failure (logarithmic right-hand scale, dots) and the LDDdetected shocking distance (left-hand scale, solid line). The dotted line shows the LDD results for a cw field $(\tau = \infty)$.

FIG. 11. (Color online) Carrier shocking for cw and pulsed (τ = 0.93) cases with multiple refractive index steps, showing the correlation in the region where $L_c \leq L_{SPM}$ between energy conservation failure (logarithmic right-hand scale, dots) and the LDD-detected shocking distance (left-hand scale, solid line). Note the narrower range of Δn as compared to the previous two graphs. The dotted line shows the LDD results for a cw field $(\tau = \infty)$.

we saw that anomalous dispersion tends to create regions of higher gradient.

The shocking region in Fig. [10](#page-5-2) has a similar outline to that of Fig. $9(b)$ $9(b)$ except that it is slightly narrower, as expected from the coherence length discussion above. However, the shocking region in Fig. [11](#page-6-0) is much narrower, especially given the change in the Δn scale. This is because the multistepped nature of the refractive index leads to a correspondingly large range of coherence lengths, with shorter ones corresponding to those spanning several steps. Since the shocking region in the multistep case has reduced in size by a factor of 2 or 3, a reasonable inference might be that the dominant coherence length results from interaction over two or three refractive index steps.

In realistic media, the refractive index will vary smoothly with frequency and the group velocity can different from the phase velocity. We can approximate this situation most simply using a refractive index gradient rather than a series of steps. The results using the LDD method in this case can be seen in Fig. [12,](#page-6-1) where now we also vary the strength of the nonlinearity. As in the previous cases, we see a well-defined shocking regime that is asymmetric about the nondispersive case.

Detailed examination shows that the curves in Fig. [12](#page-6-1) exhibit a marked similarity and can be brought into near

FIG. 12. Shocking distance vs mismatch for weak refractive index gradients δ and a range of nonlinearities. This shows an abrupt cutoff at positive Δn , but a relatively gradual one at negative Δn . The initial pulses are identical to those in Fig. [9.](#page-5-1) No cw results are shown, since the dispersion experienced by the field would be identical to the multistepped case shown in Fig. [11.](#page-6-0)

perfect coincidence by applying the scaling $\chi^{(3)} \rightarrow \chi^{(3)}/m$, $L \rightarrow mL$, and $\Delta n \rightarrow \Delta n/m$. We also get a comparable similarity for each of Figs. [9](#page-5-1)[–11,](#page-6-0) when simulations at nonlinear strengths of $\chi^{(3)}E_0^2$ =0.01 and 0.04 are added to the results. This demonstrates that the character of the shocking is dominated by the sign of interharmonic phase velocity differences, not by the local group velocity dispersion at each harmonic. Thus anomalous (normal) dispersion is primarily interesting because it gives a negative (positive) refractive index shift between successive harmonics. We leave the complicated (and far more subtle) effects of group velocity differences or dispersion for later work.

An important feature of all the results is the pronounced asymmetry, with shocking persisting much further into the anomalous dispersion regime; we have even seen it for the case of a weakly parabolic refractive index.

We can quantify this asymmetry by considering linear and nonlinear contributions to the phase matching of the harmonics (i.e., linear and nonlinear refractive index shifts), as described at the beginning of Sec. V. In the simple single step case shown in Fig. $9(b)$ $9(b)$, the first to third harmonic phase shift will dominate, because it applies to the two most intense spectral components. We can calculate the SPMinduced refractive index shift between the fundamental and third harmonic with Eqs. ([18](#page-4-2)) and ([19](#page-4-3)) to be $\Delta n_{NL:1}$ $-\Delta n_{NL:3} = -0.011$, since $\chi^{(3)}E^2 = 0.02$ at the peak of the carrier oscillations, the refractive index is $n_0^2 = 2$, and $2n_2E_1^2 = 2$ \times 3 χ ⁽³⁾E²/8*n*₀. This is roughly comparable to the offset of the shocking region, which is centred at about $\Delta n_{1,3}$ \simeq -0.014. We cannot expect perfect agreement, since the calculations ignore the role of higher-harmonic generation and depletion of the fundamental. While a simple calculation is reasonably successful in this single-step case, it cannot be applied for a realistic medium—or indeed to the situation shown in Fig. [12.](#page-6-1) There, the effects of dispersion, higherharmonic generation, and nonlinear refractive index shifts are inextricably intertwined.

To summarize, we have demonstrated that shocking is strongly dependent on the interplay between L_c and L_{SPM} , with shorter L_C 's (increasing Δn 's) decreasing the likelihood of shocking. We have also deduced the reasons for the strong *asymmetry* of the shocking region.

VII. APPLICATIONS AND EXPERIMENTS

In Secs. I and IV, we discussed how imminent carrier shocking might be recognized computationally. In considering whether shocking might be detectable experimentally, we must now decide how it might manifest itself in the laboratory. A mathematical discontinuity is clearly not a physical possibility, even if Rosen $[2]$ $[2]$ $[2]$ did manage to accommodate it theoretically, albiet at the expense of energy conservation. In practice, the increasing field gradients (and spectral broadening) that precede a shock will inevitably engender new physical processes that will limit the steepening. Indeed, we have already seen this happening in the previous two sections, where dispersion has been seen to frustrate the selfsteepening process; the next barrier would be the time scale of the nonlinear response.

FIG. 13. Numerically predicted shocking distances *Lshock* in fused silica. These are the MOC predicted distances for the wave form, assuming the dispersion was (abruptly) neglected; the shortest distance shown is about 1.9 μ m. The damage threshold for fused silica was taken to be $P_{threshold} = 50 \text{ TW/cm}^2$.

Although there is no question of a mathematical discontinuity being observed in an experiment, the recent advances in the measurment of optical pulse profiles (see, e.g., $[12]$ $[12]$ $[12]$) suggest that it might be possible to observe carrier steepening. Indeed, it has already been predicted $\lceil 4 \rceil$ $\lceil 4 \rceil$ $\lceil 4 \rceil$ that noticeable steepening effects could occur for pulses propagating in fused silica. Unfortunately, in our own simulations of this process, the LDD shock detection was not triggered at any realistic pulse intensity. Although visible steeping did occur, at no point was a seriously distorted wave form approached and the effects would have been milder if we had included the finite response time of the nonlinearity. The results pre-sented in Fig. [13](#page-7-10) show the steepest gradient recorded as a function of distance and pulse intensity for these simulations. The third harmonic coherence length for these parameters is about 7 μ m, and we can attribute the regular variation with distance seen in the figure to the third-harmonic component aligning with successive oscillations of the fundamental as the waves move across each other. The key reason why incipient shocking was not detected is because the pulse frequency lies in a region of weak normal dispersion, whereas we have shown in Sec. V that a region of weak anomalous dispersion (assuming it could be achieved) would be favorable.

The current interest in media with tailored dispersion characteristics $\begin{bmatrix} 13-15 \end{bmatrix}$ $\begin{bmatrix} 13-15 \end{bmatrix}$ $\begin{bmatrix} 13-15 \end{bmatrix}$ raises the interesting question of whether it might be possible to engineer a material that maximizes self-steepening. A major stumbling block would be the need for control over many harmonic orders; however, for a narrow-band pulse, only the dispersion characteristics close to the harmonics would be relevant, which might perhaps make the technical challenge less formidable.

The recognition that dispersion control can enhance (or reduce) carrier self-steepening suggests other applications if we widen our horizons to encompass the more general idea of carrier *shaping*. In this case, we would exploit both nonlinearity and dispersion control to optimize the shape of the carrier oscillations for a particular experiment. Applications such as high-harmonic generation (e.g., $[16]$ $[16]$ $[16]$) might well benefit from suitably designed carrier wave modulation.

VIII. CONCLUSIONS

In this paper we have investigated carrier shock formation, developed criteria for detecting its onset in numerical simulations, and shown how it is influenced by a range of parameters, particularly dispersion. We have also obtained remarkable agreement between numerical simulations and theoretical predictions of the shocking distance in the dispersionless limit and shown that the process is sensitive to both CEP and pulse duration.

Although we have confirmed that shocking occurs in a narrow parameter range, this is far from being the whole picture. In particular, there is a distinct asymmetry between the anomalous and normal dispersion regimes. The former leads to shocking signatures such as the appearance of narrow spikes as the higher harmonics interfere on the steepening part of the pulse profile. In contrast, normal dispersion creates no such features and the pulse profiles have a rather blunt appearance. The asymmetry arises from the effect of the nonlinear refractive index on the dispersion induced phase mismatch.

The conclusion to be drawn from our results is clear: if they could be engineered, materials with wide regions of weakly anomalous dispersion are much better candidates for generating steep, shocklike field profiles than those (such as silica) with a weak normal dispersion. Detecting incipient shock formation in materials like fused silica is likely to be a near impossible task, given the constraints imposed by their damage thresholds.

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